We will explain how algebraic geometry over finite fields gives rise to interesting finite groups. In order, we will borrow from:

- Milne, Algebraic Groups (2017)
- Geck, An Introduction to Algebraic Geometry and Algebraic Groups (2003)
- Carter, "On the Representation Theory of the Finite Groups of Lie Type in Characteristic 0", in *Algebra IX* (1996)

I have also drawn ideas from Brion's 2019 SCGP lectures.

## 1.1.

Start with algebraic varieties over an arbitrary algebraically closed field k. In practice, they don't form a nice category, so instead, we implicitly work in Sch<sub>k</sub>, the category of all schemes of finite type over k.

An *algebraic group* over k ought to be a group object in  $Sch_k$ : This entails maps  $m : G \times G \to G$  and  $e : Spec k \to G$  and  $i : G \to G$  satisfying certain axioms. Some authors add more adjectives, especially smoothness. Examples of affine algebraic groups:

$$\mathbf{G}_a$$
,  $\mathbf{G}_m$ ,  $\mu_n$ ,  $\mathrm{GL}_n$ ,  $\mathrm{Sp}_{2n}$ ,  $\mathrm{Aff}_n := \mathrm{GL}_n \ltimes \mathbf{G}_a^n$ .

Examples of non-affine algebraic groups: Abelian varieties, like elliptic curves. They are precisely the connected, smooth, proper algebraic groups. Barsotti–Chevalley says that if k is *perfect*, then any connected, smooth algebraic group over k is an extension of an abelian variety by an affine algebraic group, in the sense that we will define below.

*Remark* 1.1. By Milne Prop. 1.28 and Prop. 1.37, the following conditions on an algebraic group G over k are equivalent:

- (1) G is smooth.
- (2) G is reduced.
- (3) Its *k*-dimension equals that of its tangent space at the identity, *i.e.*, its Lie algebra.

For example: If  $k = \overline{\mathbf{F}}_p$  for some prime p, then  $\mu_n = \operatorname{Spec} k[t]/(t^n - 1)$ , the algebraic group of *n*th roots of unity, is smooth if and only if  $p \nmid n$ . When is it connected?

1.2.

An affine algebraic group G is controlled by its coordinate ring k[G]. The multiplication on G corresponds to a coproduct  $\Delta : k[G] \rightarrow k[G] \otimes k[G]$  satisfying certain axioms. Similarly, if V is a vector space over k, then a

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representation of G on V given by action morphism  $G \times V \to V$  in  $\operatorname{Sch}_k$  corresponds to a *coaction* morphism  $k[V] \to k[G] \otimes k[V]$  satisfying certain axioms. The linearity of the G-action on V corresponds to the coaction restricting to a morphism  $V^{\vee} \to k[G] \otimes V^{\vee}$ . In this case,  $V^{\vee}$  is an example of what we call a k[G]-comodule.

One can check that any k[G]-comodule M is a filtered union of its finitedimensional sub-comodules. The key idea is that the coaction map must send any vector to a finite sum of tensors. In particular, taking M = k[G], we can find a finite-dimensional sub-comodule  $M' \subseteq M$  that contains a generating set for k[G] as a k-algebra. If we now write  $M' = V^{\vee}$ , then V turns out to be a finitedimensional representation of G such that the induced map  $k[GL(V)] \rightarrow k[G]$ is surjective. See Milne Chapter 4 for the details of the proof. Altogether:

**Theorem 1.2.** Any affine algebraic group is linear: a closed subgroup of GL(V) for some V.

**Example 1.3.** In the coordinates

$$\operatorname{GL}_2 = \left\{ \begin{pmatrix} a & b \\ c & d \end{pmatrix} \middle| \det \neq 0 \right\},\,$$

we have  $k[GL_2] = k[a, b, c, d][det^{-1}]$ . The formulas that describe the coaction of  $k[GL_2]$  on itself, *i.e.*, the comultiplication  $\Delta$ , correspond to the formulas that describe matrix multiplication: *e.g.*,  $a \mapsto a \otimes a + b \otimes c$ .

Let V be the vector space of all  $2 \times 2$  matrices. Then  $V^{\vee} = k \langle a, b, c, d \rangle$  is a sub-comodule of  $k[GL_2]$  viewed as a comodule over itself. The fact that it contains a generating set for  $k[GL_2]$  as an algebra reflects the fact that the representation of  $GL_2$  on V by multiplication is faithful.

## 1.3.

The preceding discussion suggests that we should study specific algebraic groups that embed into  $GL_n$ . To this end, we transfer various definitions from group theory to the world of algebraic groups.

A homomorphism of algebraic groups  $\varphi : H \to G$  is a morphism in Sch<sub>k</sub> that takes the multiplication on H to that on G. The kernel of  $\varphi$  is its fiber over the identity of G. When the kernel is trivial, we say that H is an algebraic subgroup of G. In this case, we claim that  $\varphi$  is a closed embedding. Indeed, one can check that the Zariski closure of H(k) in G(k) is a group inside which H(k) has finite index, which forces H(k) to coincide with the closure.

We say that an algebraic subgroup  $N \subseteq G$  is *normal* if and only if it is the kernel of some homomorphism. In this case, the fppf sheaf quotient G/N is represented by an algebraic group, called the *quotient* of G by N. The map

 $G \rightarrow G/N$  is faithfully flat, or more simply, flat and surjective. Note that if G/N is smooth, then flatness follows from the generic flatness theorem via a homogeneity argument.

Having defined subgroups and quotients, we can now make sense of *extensions* of algebraic groups, *semidirect products*, *etc.*, and analogues of the isomorphism theorems from group theory. See Milne Chapter 5 for details.

1.4.

In the first lecture, we mentioned the algebraic subgroup of upper-triangular matrices  $B \subseteq GL_n$ . Note that the derived subgroup of B(k) is precisely U(k), where  $U \subseteq B$  is the algebraic subgroup of *unipotent* upper-triangular matrices. Moreover,  $B(k) \simeq T(k) \ltimes U(k)$ , where  $T \subseteq B$  is the algebraic subgroup of diagonal matrices.

In any algebraic group H, we define the *derived subgroup*  $[H, H] \subseteq H$  to be the intersection of all normal subgroups of H with abelian quotient. We can check that U = [B, B], and that  $B \simeq T \ltimes U$ . With more work, we can check that B is *solvable* in the sense that its derived series has finite length.

In general: A *torus* is an algebraic group isomorphic to a power of  $G_m$ . By Milne Prop. 16.2, any connected, solvable affine algebraic group *B* decomposes as  $T \ltimes [B, B]$ , where *T* is a torus. By Milne Thm. 16.27, any other maximal torus of *B* is conjugate to *T* under B(k).

We say that *B* is a *Borel subgroup* of an algebraic group *G* if and only if it is maximal among connected, smooth, solvable algebraic subgroups of *G*. Following Milne, a *Borel pair* or *Killing pair* of *G* is a choice of pair (B, T), where *B* is a Borel subgroup and *T* is any maximal torus of *B*. Later we will sketch a proof of:

**Theorem 1.4** (Cartan–Lie–Kolchin). In any connected, smooth, affine algebraic group G, any two Borel pairs are conjugate under G(k).

By this theorem, a connected, smooth, affine algebraic group is solvable, *resp*. unipotent, if and only if it has a faithful representation whose image is contained in the algebraic subgroup of arbitrary, *resp*. unipotent, upper-triangular matrices.

In any affine algebraic group G, the maximal connected, smooth normal subgroup that is solvable, *resp.* unipotent, is called the *radical*, *resp. unipotent radical* of G. We say that G is *semisimple*, *resp. reductive*, if and only if it has trivial radical, *resp.* unipotent radical. Thus semisimple implies reductive. The groups  $SL_n$  are semisimple; the groups  $GL_n$  are reductive but not semisimple.

*Remark* 1.5. The definition of a semisimple algebraic group matches up in a precise sense with that of a semisimple Lie algebra.<sup>1</sup> Recall that *complex* 

<sup>&</sup>lt;sup>1</sup>See https://math.stackexchange.com/q/1982569.

semisimple Lie algebras are classified by Dynkin diagrams.

However, the definition of a reductive algebraic group does not match up in this manner with that of a reductive Lie algebra. A better viewpoint is: The reductive algebraic groups over  $\mathbf{C}$  are precisely the complexifications of the compact real Lie groups.<sup>2</sup> By work of Chevalley, the classification of reductive algebraic groups is the same over any (algebraically closed) field.

1.5.

Now we focus on affine algebraic groups over the algebraic closure of a finite field: say, G over  $k = \bar{\mathbf{F}}_q$ . We want to construct finite groups that look like  $GL_n(\mathbf{F}_q)$ , but starting from geometry over k rather than  $\mathbf{F}_q$  itself, because to the eye of an algebraic geometer, k is the simpler field.

Note that a scheme over k cannot have nontrivial  $\mathbf{F}_q$ -points. What we are actually doing is first choosing a scheme  $G_1$  over  $\mathbf{F}_q$  such that  $G_1 \otimes k = \mathrm{GL}_n$ , then taking the set of  $\mathbf{F}_q$ -points of  $G_1$ . One choice gives  $\mathrm{GL}_n(\mathbf{F}_q)$ . As it turns out, another choice gives a different group called  $\mathrm{U}_n(\mathbf{F}_q)$ .

If X, resp.  $X_1$ , is a scheme over k, resp.  $\mathbf{F}_q$ , and  $\alpha$  is an isomorphism  $X \to X_1 \otimes k$ , then we say that  $(X_1, \alpha)$  is a *descent of* X to  $\mathbf{F}_q$ , or an  $\mathbf{F}_q$ -rational structure on X. If X is an algebraic group and its multiplication, identity, and inversion maps descend to  $X_1$  along  $\alpha$ , then we say that  $(X_1, \alpha)$  is an  $\mathbf{F}_q$ -form of X. Abusing notation, we will omit mention of  $\alpha$  where convenient.

*Remark* 1.6. Most texts define algebraic groups in the setting of arbitrary fields. For clarity, I will try to speak only of algebraic groups over fields that are algebraically closed, and of forms of these groups over subfields.

Let  $\sigma_X : X \to X$  and  $\sigma_{X_1} : X_1 \to X_1$  be the morphisms that fix the underlying topological spaces and are given by  $f \mapsto f^q$  on sections of the structure sheaves. By Fermat's Little Theorem, these are morphisms over  $\mathbf{F}_q$ . Let  $F : X \to X$  be the morphism over k given by the transport of  $\sigma_{X_1} \otimes \operatorname{id}_k$  along  $\alpha$ . We refer to F as the *(relative) Frobenius map* on X induced by  $(X_1, \alpha)$ . By construction,

$$\sigma_X = (\mathrm{id}_{X_1} \otimes \sigma_{\mathrm{Spec}\,k}) \circ F = F \circ (\mathrm{id}_{X_1} \otimes \sigma_{\mathrm{Spec}\,k}).$$

We claim that we can recover  $X_1$  up to isomorphism from X and F. Indeed, if X = Spec A, then we can take

$$X_1 = \text{Spec } A_1, \text{ where } A_1 = \{ f \in A \mid F^*(f) = f^q \}$$

The general case follows from the affine one by gluing. Ultimately,  $\mathbf{F}_q$ -rational structures on X are classified by their Frobenius maps.

<sup>&</sup>lt;sup>2</sup>See https://mathoverflow.net/q/299143.

Note that an  $\mathbf{F}_q$ -rational structure  $G_1$  of G is an  $\mathbf{F}_q$ -form if and only if the corresponding Frobenius map F satisfies  $F(g \cdot h) = F(g) \cdot F(h)$  for all  $g, h \in G$ . More generally, if X is a k-scheme equipped with a G-action, then Frobenius maps F on G and X are called *compatible* if and only if  $F(g \cdot x) = F(g) \cdot F(x)$  for all  $x \in X$ .

For an approach that starts from an abstract definition of relative Frobenius maps, then recovers  $\mathbf{F}_q$ -rational structures, see Section 4.1 of Geck's book.

**Example 1.7.** Write  $\mathbf{G}_m = \operatorname{Spec} k[t^{\pm 1}]$ . There is a Frobenius map  $F : \mathbf{G}_m \to \mathbf{G}_m$  given by  $F^*(t) = t^q$ , corresponding to the  $\mathbf{F}_q$ -form arising from  $\mathbf{F}_q[t^{\pm 1}]$ .

Now suppose that  $\mathbf{F}_q$  does not contain  $i := \sqrt{-1}$ . In particular,  $2 \nmid q$ . Here the algebra  $A_1 = \mathbf{F}_q[a, b]/(a^2 + b^2 - 1)$  is not isomorphic to  $\mathbf{F}_q[t^{\pm 1}]$ , yet we do have an isomorphism  $A_1 \otimes k \simeq k[t^{\pm 1}]$  given by  $a = \frac{1}{2}(t + t^{-1})$  and  $b = \frac{1}{2i}(t - t^{-1})$ . What is the Frobenius map on  $\mathbf{G}_m$  that corresponds to  $A_1$ ? We claim that it is F defined by  $F^*(t) = t^{-q}$ . Indeed,  $F^*(a) = a^q$ , and since  $i^q = -i$  by hypothesis,  $F^*(b) = b^q$ .

In fact, the group structure on  $\mathbf{G}_m$  descends to Spec  $A_1$ . The resulting  $\mathbf{F}_q$ -form of  $\mathbf{G}_m$  is the *circle group* 

$$U(1) := \left\{ \begin{pmatrix} a & -b \\ b & a \end{pmatrix} \middle| a^2 + b^2 = 1 \right\}.$$

It generalizes to an  $\mathbf{F}_q$ -form of  $\operatorname{GL}_n$  called the  $n \times n$  general unitary group and denoted  $\operatorname{GU}(n)$ . Compare to Geck, §1.5.12 and §4.1.10(c).

## 1.6.

Suppose that  $F : X \to X$  is a Frobenius map corresponding to an  $\mathbf{F}_q$ -rational structure  $X_1$ . It acts on  $X(\bar{\mathbf{F}}_q)$ , viewed as the set of sections Spec  $\bar{\mathbf{F}}_q \to X$ , by postcomposition. We have bijections

$$X^F(\overline{\mathbf{F}}_q) \simeq X(\overline{\mathbf{F}}_q)^F \simeq X_1(\mathbf{F}_q).$$

In Deligne–Lusztig theory, people write  $X^F$  to denote the set  $X^F(\bar{\mathbf{F}}_q)$  as well as the scheme.

Returning to algebraic groups, we see that by running over all possible choices of q, G, and  $F : G \to G$  respecting the group structure on G, we get a large supply of finite groups  $G^F$ . Which are the most fundamental?

Recall that a finite group is *simple* if and only if it has no nontrivial proper normal subgroup. Remarkably, many of the finite simple groups are closely related to groups of the form  $G^F$ , though not necessarily of that form themselves.

**Theorem 1.8** (Classification). Every finite simple group is one of these:

(1) A cyclic group of prime order.

- (2) An alternating group  $A_n$  with  $n \ge 5$ .
- (3) A finite simple "group of Lie type".
- (4) One of 26 (or 27) sporadic groups.

What is a finite group of Lie type? Unfortunately, there is no widely accepted definition,<sup>3</sup> but morally, these are the groups that are most closely related to the groups  $G^F$ . Class (1) could have been folded into class (3), but wasn't (for good reason), and the controversy over the number of sporadic groups is a similar issue. The finite simple groups of Lie type themselves fall into subclasses:

(1) Chevalley groups

$$A_n(q), B_n(q) \text{ for } n \ge 2, \quad C_n(q) \text{ for } n \ge 3, \quad D_n(q) \text{ for } n \ge 4,$$
  
 $E_n(q) \text{ for } n = 6, 7, 8, \quad F_4(q), \quad G_2(q).$ 

(2) Steinberg groups

$${}^{2}A_{n}(q^{2})$$
 for  $n \ge 2$ ,  ${}^{2}D_{n}(q^{2})$  for  $n \ge 4$ ,  ${}^{2}E_{6}(q^{2})$ ,  ${}^{3}D_{4}(q^{3})$ .

(3) Suzuki groups  ${}^{2}B_{2}(2^{2m+1})$  and Ree groups  ${}^{2}G_{2}(3^{2m+1})$ .

(4) The Tits group  ${}^{2}F_{4}(2^{2m+1})$ , sometimes counted as the 27th sporadic.

Above:

The Chevalley and Steinberg groups are all central quotients either of certain groups  $G^F$  or kernels of such groups along determinant or spinor norm maps. The Chevalley groups come from split  $\mathbf{F}_q$ -forms, while the Steinberg groups come from nonsplit forms—terms we will define later.

The Suzuki and Ree groups all take the form  $G^F$ , where F is a Frobenius map in a more general sense than we introduced earlier: Again, see Geck Chapter 4. They can also be constructed as fixed-point subgroups of groups  $G^F$  under exotic automorphisms, where F is a Frobenius map in our earlier sense, arising from some q and some  $\mathbf{F}_q$ -form of G. The Tits group also fits into this latter construction.

The notation for the finite simple groups of Lie type hints that the associated pairs (G, F) are very special. The group G is always *almost-simple*: This means G is semisimple, noncommutative, and has no connected, smooth normal subgroups other than itself and {1}. In particular, via the classification of semisimple Lie algebras, it comes from a connected Dynkin diagram. The map F then comes from an automorphism of this Dynkin diagram.

*Remark* 1.9. Some authors refer to *almost-simple* algebraic groups as *simple* algebraic groups. However, this notion is not quite analogous to that of a simple (abstract) group.

<sup>&</sup>lt;sup>3</sup>See https://mathoverflow.net/q/136880.